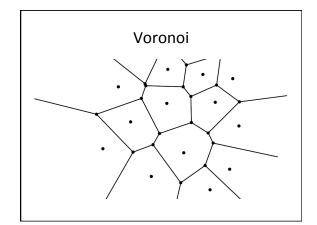
#### **Computational Geometry**

Medial Axis
Straight Skeleton

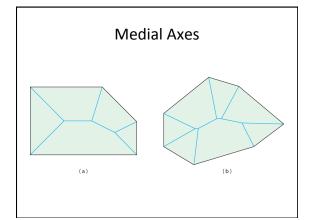


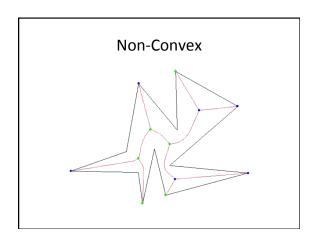
#### **Alternative Voronoi Definitions**

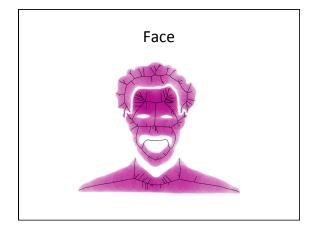
- Vor(S) is the locus of centers of maximal empty circles those whose interior contain no site of S.
- Vor(S) is the locus of points to which there are two or more nearest sites
- Vor(S) is the set of "quench points" if the plane is burned uniformly and simultaneously from all sites in S.

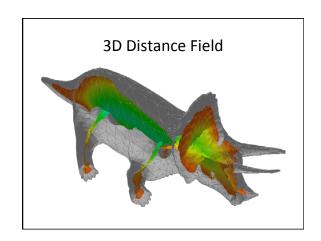
#### Definition

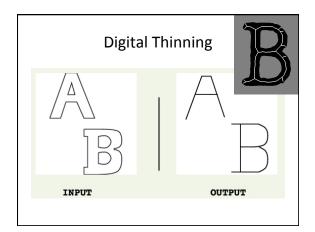
- The medial axis M(P) of a polygon P is the closure of the set of points in P that have two or more closest points among the points on δP.
- This also known as the  $\it cut\ locus$  of  $\it \delta P$  in Mathematics.





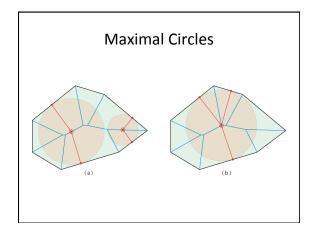


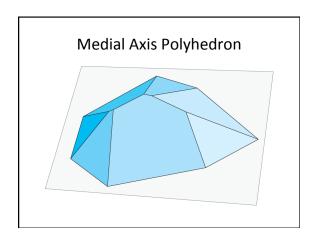




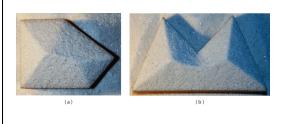
# Medial Axis of a Convex Polygon

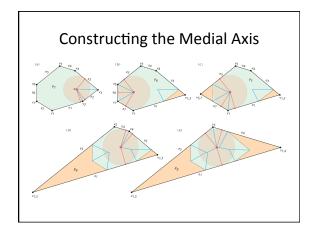
- A geometric tree of straight segments whose leaves are the vertices of P.
- Points on the medial axis are centers of maximal circles that touch  $\delta P$  in two or more points.
- Starting a fire  $\delta P$  and burning into the interior would again result in the "quench points" being the medial axis.





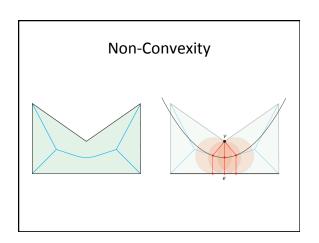
# Sand-constructed Physical Models





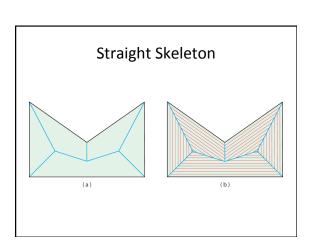
### **Time Complexity**

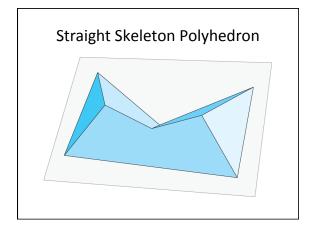
- Find the first pair of intersecting bisectors by checking all pairs of adjacent vertices – O(n)
- Recursion
- O(n<sup>2</sup>)
- O(nlogn) is possible with data structure (priority queue)
- O(n) possible with considerably more work and cleverness



# Straight Skeleton

- shrink  $\delta P$  via parallel transformation of all edges inward
- each vertex (including reflex) follows the angle bisector
- stop when
  - an edge is 0 length
  - a reflex vertex collides with an edge pinch into two polygons and continue





# Notes

- Voronoi definition does not hold
- Best algorithm runs in  $O(n^{17/11})$
- Unsolved in 3D (2008)
- Unsolved for higher dimensions