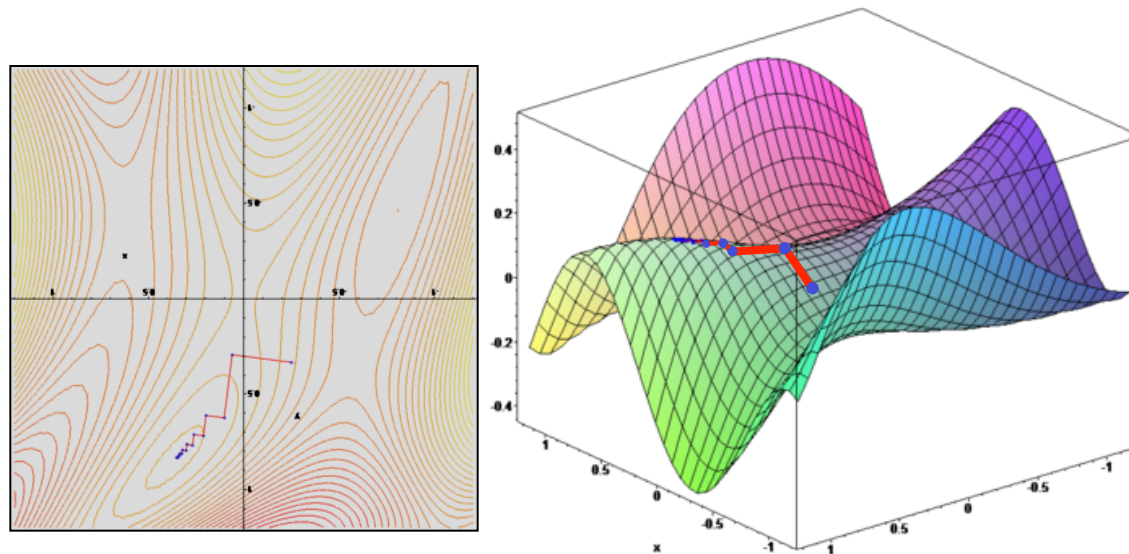


Gradient ascent / descent



Images from http://en.wikipedia.org/wiki/Gradient_descent

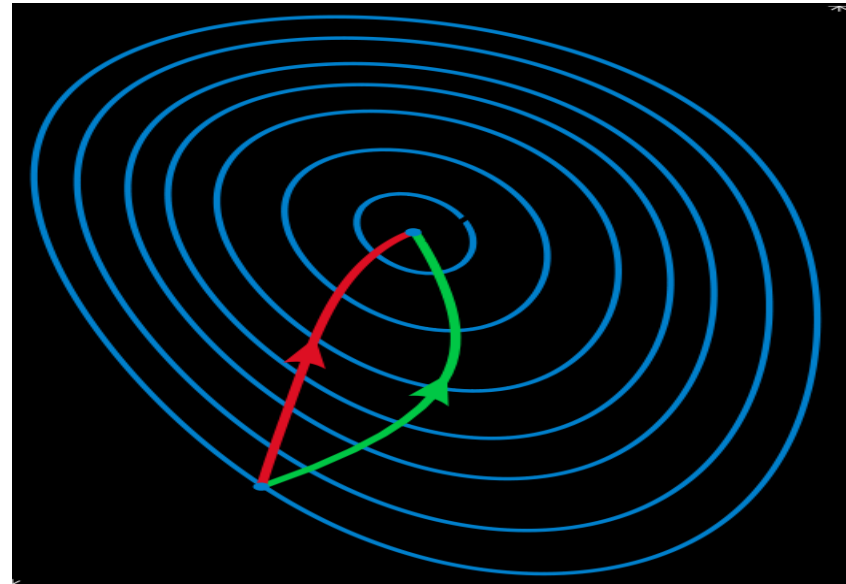
- Gradient descent procedure for finding the $\arg_x \min f(x)$
 - choose initial x_0 randomly
 - repeat
 - $x_{i+1} \leftarrow x_i - \eta f'(x_i)$
 - until the sequence $x_0, x_1, \dots, x_i, x_{i+1}$ converges
- Step size η (eta) is small (perhaps 0.1 or 0.05)

Gradient methods vs. Newton's method

- A reminder of Newton's method from Calculus:

$$x_{i+1} \leftarrow x_i - \eta f'(x_i) / f''(x_i)$$

- Newton's method uses 2nd order information (the second derivative, or, curvature) to take a more direct route to the minimum.
- The second-order information is more expensive to compute, but converges quicker.



Contour lines of a function
Gradient descent (green)
Newton's method (red)

Image from http://en.wikipedia.org/wiki/Newton's_method_in_optimization

Exploring the Landscape

- **Local Maxima:** peaks that aren't the highest point in the space
- **Plateaus:** the space has a broad flat region that gives the search algorithm no direction (random walk)
- **Ridges:** flat like a plateau, but with drop-offs to the sides; steps to the North, East, South and West may go down, but a step to the NW may go up.

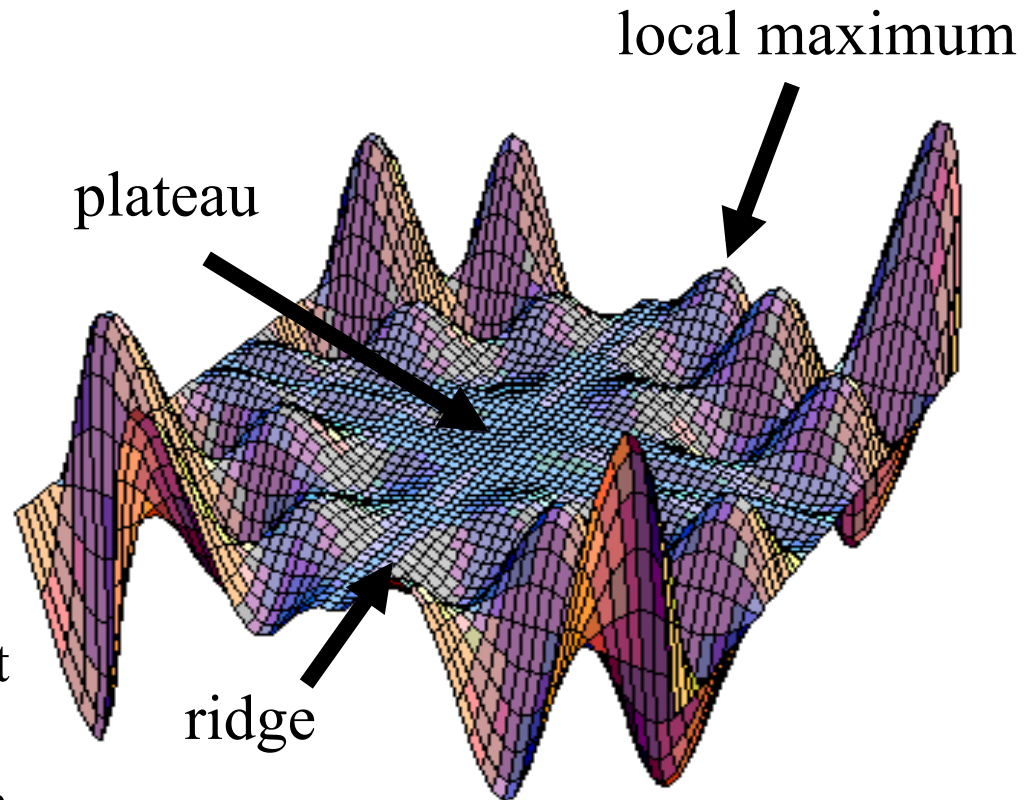


Image from: <http://classes.yale.edu/fractals/CA/GA/Fitness/Fitness.html>

Simulated annealing

- Simulated annealing (SA) exploits an analogy between the way in which a metal cools and freezes into a minimum-energy crystalline structure (the annealing process) and the search for a minimum [or maximum] in a more general system.
- SA can avoid becoming trapped at local minima.
- SA uses a random search that accepts changes that increase objective function f , **as well as** some that **decrease** it.
- SA uses a control parameter T , which by analogy with the original application is known as the system “**temperature.**”
- T starts out high and gradually decreases toward 0.

Simulated annealing (cont.)

- A “bad” move from A to B is accepted with a probability

$$P(\text{move}_{A \rightarrow B}) = e^{(f(B) - f(A)) / T}$$

- The higher the temperature, the more likely it is that a bad move can be made.
- As T tends to zero, this probability tends to zero, and SA becomes more like hill climbing
- If T is lowered slowly enough, SA is complete and admissible.

The simulated annealing algorithm

function SIMULATED-ANNEALING(*problem, schedule*) **returns** a solution state

inputs: *problem*, a problem

schedule, a mapping from time to “temperature”

static: *current*, a node

next, a node

T, a “temperature” controlling the probability of downward steps

current $\leftarrow$ MAKE-NODE(INITIAL-STATE[*problem*])

for *t* $\leftarrow$ 1 **to** ∞ **do**

T $\leftarrow$ *schedule*[*t*]

if *T*=0 **then return** *current*

next $\leftarrow$ a randomly selected successor of *current*

$\Delta E \leftarrow$ VALUE[*next*] – VALUE[*current*]

if $\Delta E > 0$ **then** *current* $\leftarrow$ *next*

else *current* $\leftarrow$ *next* only with probability $e^{\Delta E/T}$