Introduction to Information Theory

Part 4















Error Detection by Repetition

In the presence of 20% noise...

Message: \$ 5 2 1 3 . 7 5Transmission 1: \$ 5 2 9 3 . 7 5Transmission 2: \$ 5 2 1 3 . 7 5Transmission 3: \$ 5 2 1 3 . 1 1Transmission 4: \$ 5 4 4 3 . 7 5Transmission 5: \$ 7 2 1 8 . 7 5

There is no way of knowing where the errors are.

















Mutual Information

• The mutual information of a random variable *X* given the random variable *Y* is

I(X;Y) = H(X) - H(X|Y)

It is the information about X transmitted by Y.

Mutual Information: Properties

- I(X;Y) = H(X,Y) H(X|Y) H(Y|X)
- I(X;Y) = H(X) H(X|Y)
- I(X;Y) = H(Y) H(Y|X)
- *I*(*X*; *Y*) is symmetric in *X* and *Y*
- $I(X;Y) = \sum_{x} \sum_{y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$
- I(X;Y) >= 0

•
$$I(X;X) = H(X)$$









Channel Capacity

 $c = \max_{input \ probabilities} I(X;Y)$

Mutual information about X given Y is the information transmitted by the channel and depends on the probability structure

- Input probabilities

- Transition probabilities
- Output probabilities

















Error Correcting Codes

- Hamming Codes (1950)
- Linear Codes
- Low Density Parity Codes (1960)
- Convolutional Codes
- Turbo Codes (1993)



Applications of Error Correcting Codes

- Satellite communications
- Spacecraft/space probe communications: Mariner 4 (1965), Voyager (1977-), Cassini (1990s), Mars Rovers (1997-)
- CD and DVD Players, etc.
- Internet & Web communications (Ethernet, IP, IPv6, TCP, UDP, etc)
- Data storage
- ECC Memory (DRAM)
- Etc. etc. etc.

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Error Correcting Codes: Checksum

- ISBN: 0-691-12418-3
- 1*0+2*6+3*9+4*1+5*1+6*2+7*4+8*1+9*8
 = 168 mod 11 = 3
- This is a staircase checksum















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