

CS312

OpenGL

Viewing Transformations and
Projections

[Controlling states]

- Enabling features

```
glEnable (GL_DEPTH_TEST) ;
```

- Setting state

```
glShadeModel (GL_FLAT) ;
```

```
glShadeModel (GL_SMOOTH) ;
```

[OpenGL Buffers]

- Color buffer
 - Front and back
- Depth buffer (z-buffer)
 - Hidden surface removal
- Clearing buffers
 - `glClearColor (r , g , b , a) ;`
 - `glClearDepth (1 . 0) ;`
 - `glClear (GL_COLOR_BUFFER_BIT |
GL_DEPTH_BIT) ;`

[Depth Buffering]

- Request a depth buffer

```
glutInitDisplayMode (GLUT_DEPTH | ... ) ;
```

- Enable depth buffering

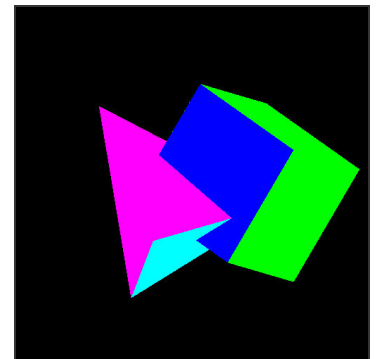
```
glEnable (GL_DEPTH_TEST) ;
```

- Clear color and depth buffers

```
glClear (GL_COLOR_BUFFER_BIT |  
        GL_DEPTH_BUFFER_BIT) ;
```

- Render scene

- Swap color buffers

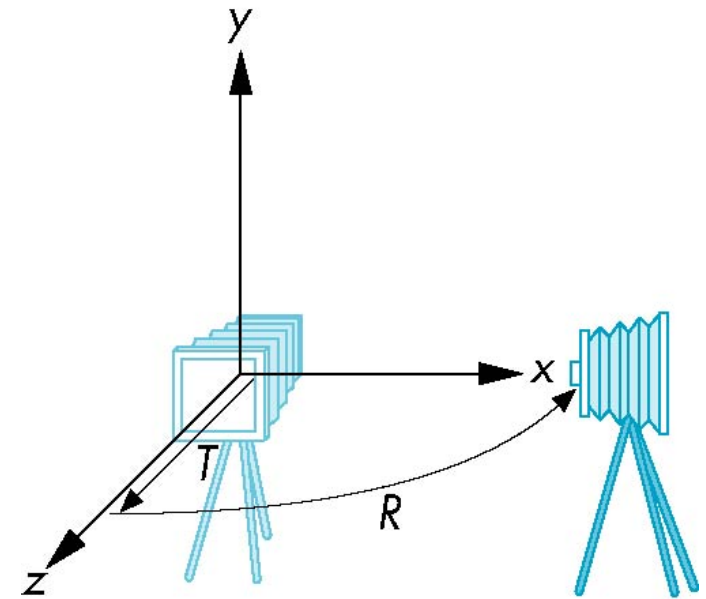


[Moving the Camera]

- The First Approach:
 - Specify the position indirectly by applying a sequence of rotations and translations to the model-view matrix.
 - This is a direct application of the geometric transformations.

[Moving the Camera]

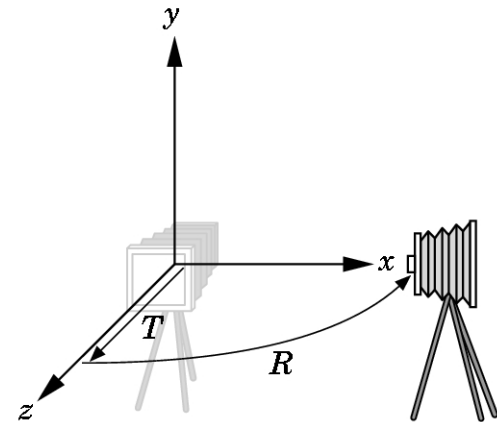
- We can move the camera to any desired position by a sequence of rotations and translations
- Example: side view
 - Rotate the camera
 - Move it away from origin
 - Model-view matrix $C = TR$



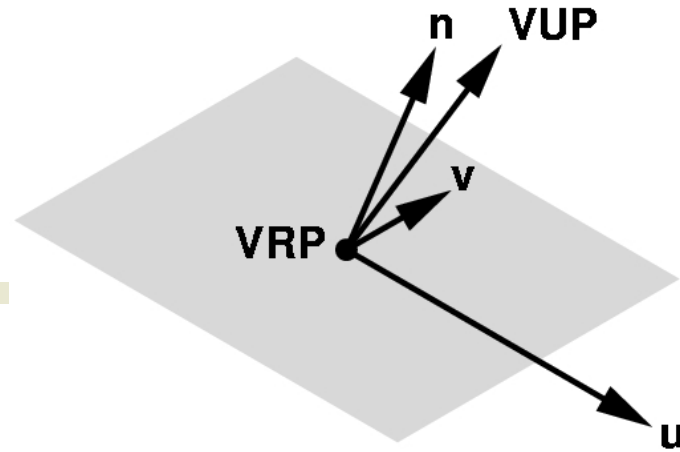
[Moving the Camera]

- We must be careful for two reasons:
 - First, we usually want to define the camera before we position the objects in the scene.
 - Second, transformations on the camera may appear to be backward from what we might expect.

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glTranslatef(0.0, 0.0, -d);  
glRotatef(-90.0, 0.0, 1.0, 0.0)
```



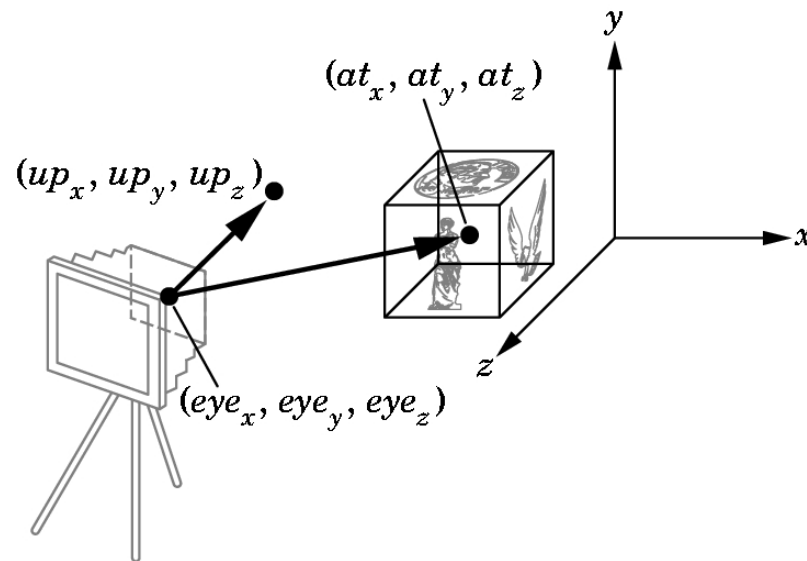
[Viewing APIs



- We can take a different approach to positioning the camera – We describe the camera's position and orientation in the world frame
 - It's desired location is centered at the view-reference point (VRP)
 - It's orientation is specified with the view-plane normal (VPN) and the view-up vector (VUP)

[gluLookAt]

- GL uses a more direct method, fortunately.



- `gluLookAt(eyex, eyey, eyez, atx, aty, atz, upx, upy, upz);`

[gluLookAt]

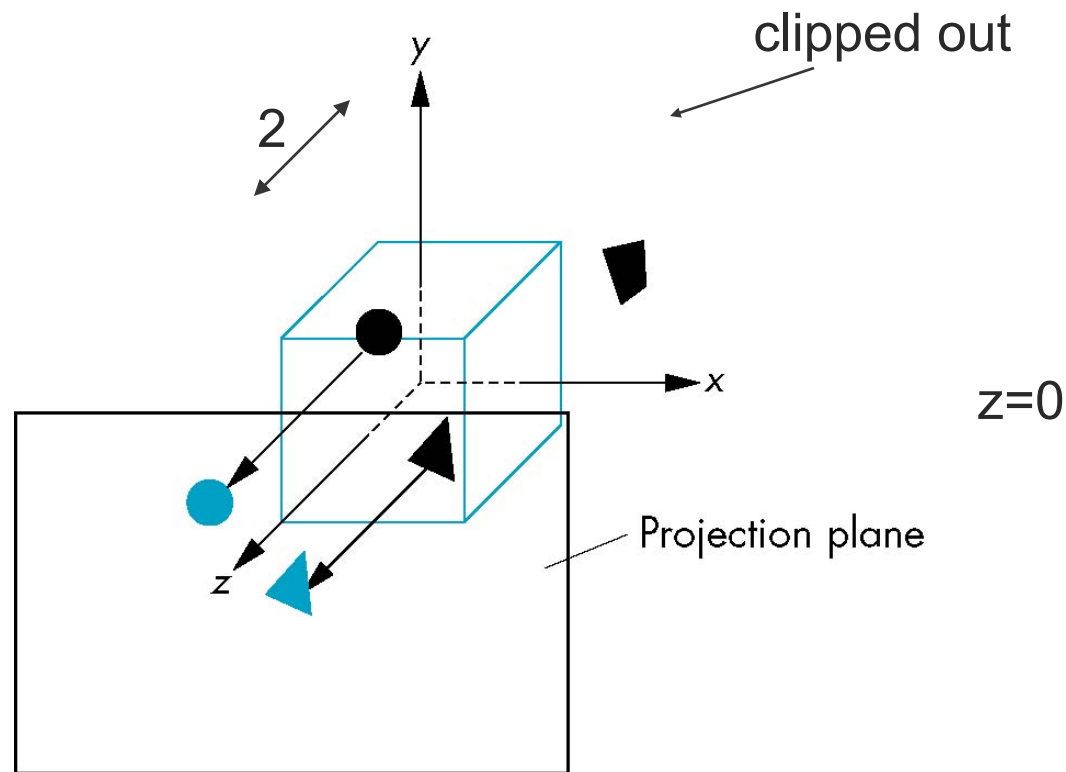
```
glMatrixMode(GL_MODELVIEW) ;  
glLoadIdentity( ) ;  
gluLookAt(...) ;  
  
//transformations  
//draw ojects
```

[The OpenGL Camera]

- In OpenGL, initially the world and camera frames are the same
 - Default model-view matrix is an identity
- The camera is located at origin and points in the negative z direction
- OpenGL also specifies a default view volume that is a cube with sides of length 2 centered at the origin
 - Default projection matrix is an identity

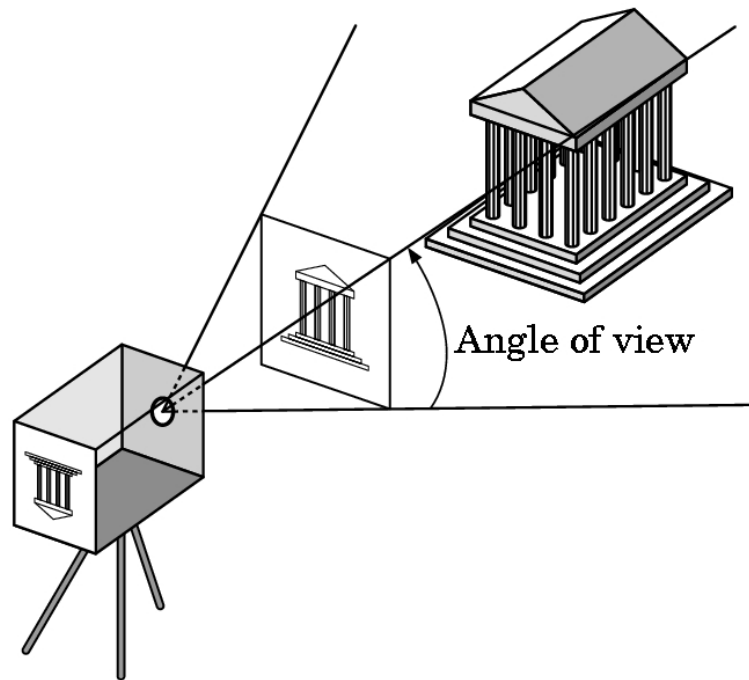
[Default Projection]

Default projection is orthogonal



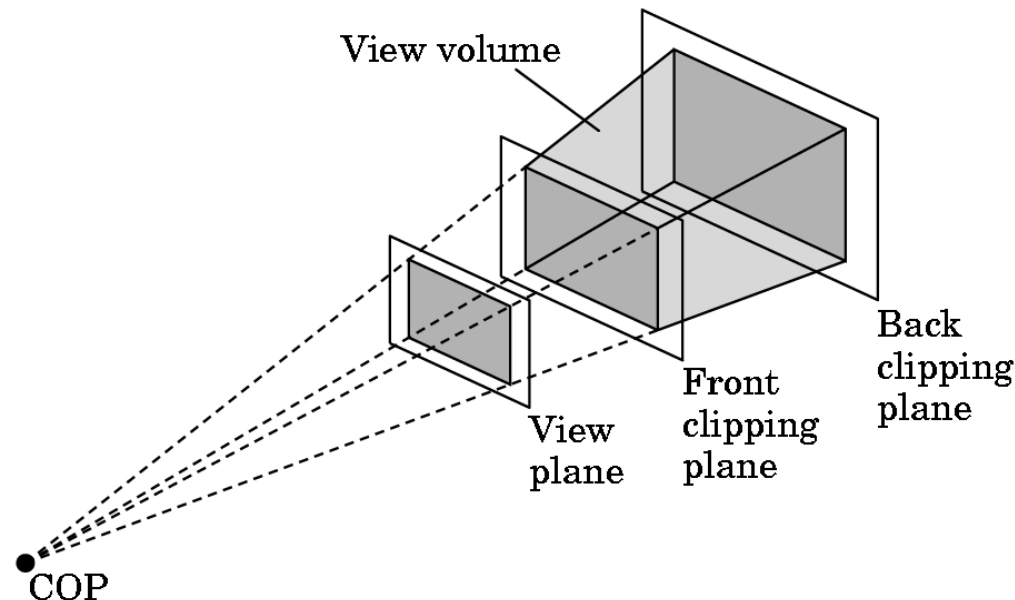
[Projections in OpenGL]

- The View Volume



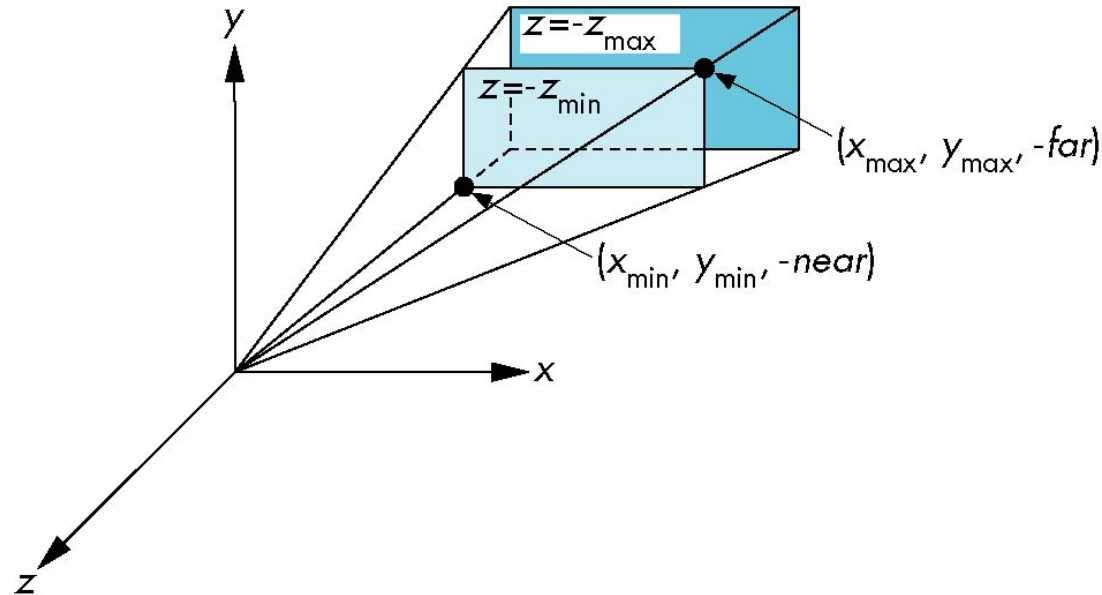
[Frustum]

- Define clipping parameters through the specification of a projection.
- The resulting view volume is a frustum – which is a truncated pyramid.



[Perspectives in OpenGL]

- OpenGL has two functions for specifying perspective views
 - `glFrustum(xmin, xmax, ymin, ymax, near, far);`



[Current Matrix]

- The projection matrix determined by these specifications multiplies the present matrix.

- A typical sequence

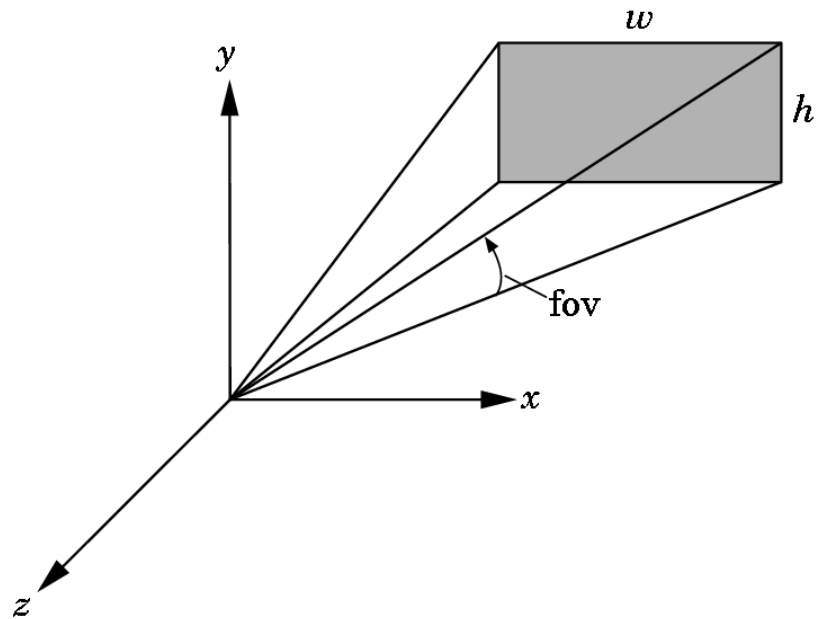
```
glMatrixMode(GL_PROJECTION);
```

```
glLoadIdentity();
```

```
glFrustum(xmin, xmax, ymin,  
          ymax, near, far);
```

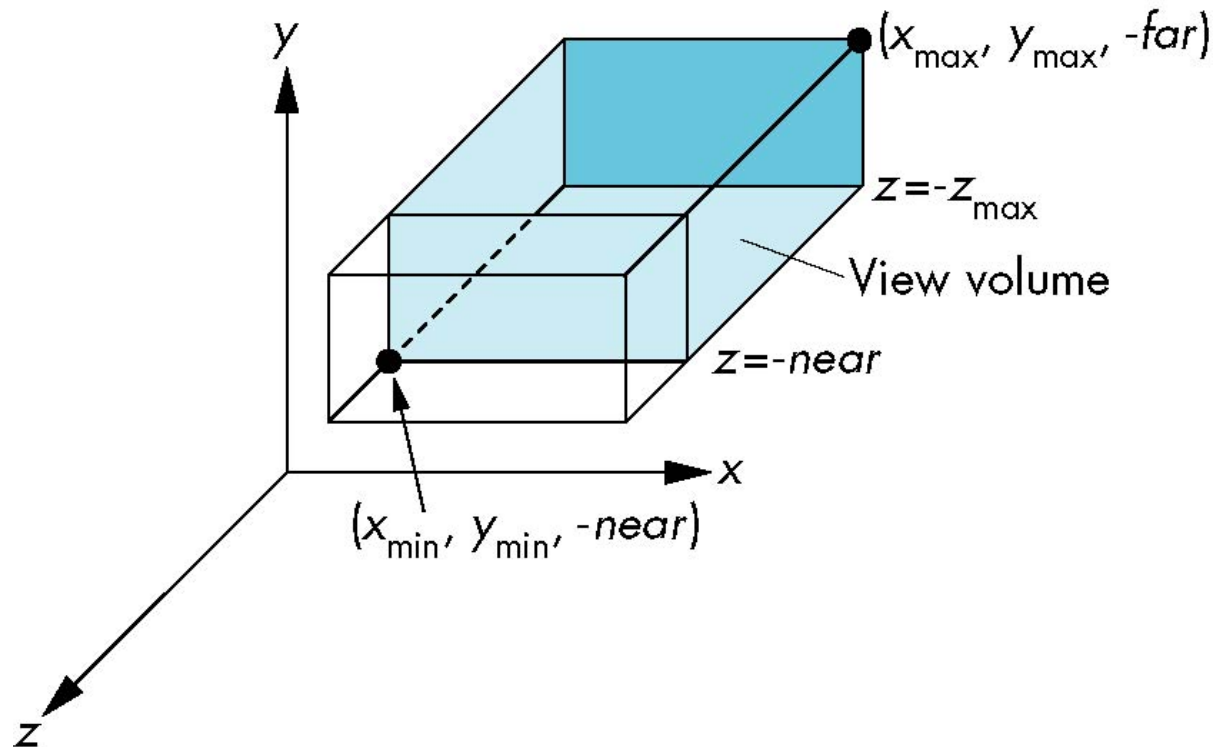

[Field of View]

- `gluPerspective(fovy, aspect, near, far);`



[Parallel Viewing in OpenGL]

- `glOrtho(xmin, xmax, ymin, ymax, near, far);`



[glut 3D Primitives]

■ Cube

- `void glutSolidCube (GLdouble size);`
- `void glutWireCube (GLdouble size);`

■ Sphere

- `void glutSolidSphere (GLdouble radius, GLint slices, GLint stacks);`
- `void glutWireSphere (GLdouble radius, GLint slices, GLint stacks);`

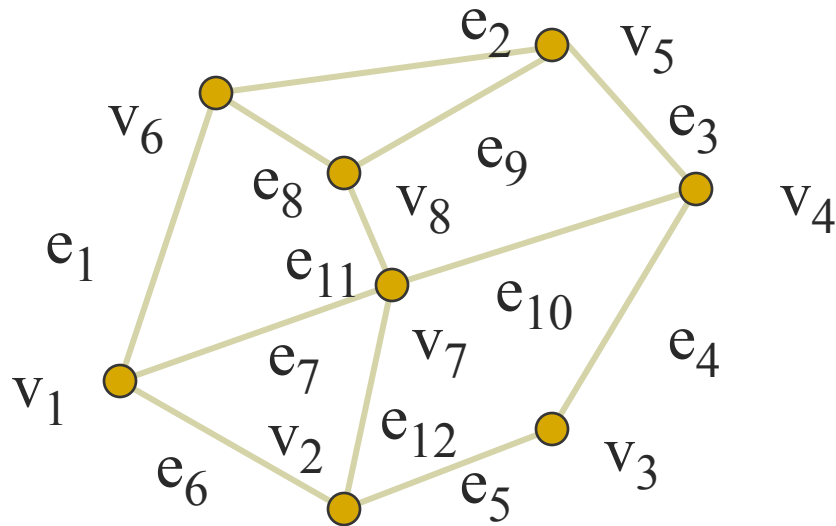
[glut 3D Primitives]

- Teapot
 - `void glutSolidTeapot (GLdouble size) ;`
 - `void glutWireTeapot (GLdouble size) ;`
- Many other geometric shapes

[Defining your own shapes]

- Objects are surfaces – hollow inside
- Objects are approximated by flat, convex polygons
- Each of these polygons (faces) is given by a set of 3D vertices
- This set of vertices and how they connect (edges) is known as a mesh

[Representing a Mesh]



- There are 8 nodes and 12 edges
 - 5 interior polygons
 - 6 interior (shared) edges
- Each vertex has a location $v_i = (x_i \ y_i \ z_i)$

[Simple Representation]

- Define each polygon by the geometric locations of its vertices

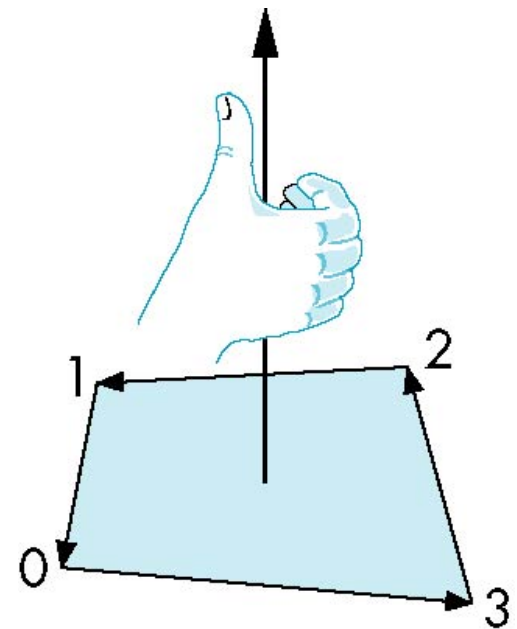
```
glBegin (GL_POLYGON) ;  
    glVertex3f (x1, y1, z1) ;  
    glVertex3f (x2, y2, z2) ;  
    glVertex3f (x7, y7, z7) ;  
glEnd () ;
```

- Inefficient and unstructured
 - Consider moving a vertex to a new location

Inward and Outward Facing Polygons

- $\{v_0, v_3, v_2, v_1\}$ and $\{v_1, v_0, v_3, v_2\}$ are equivalent in that the same polygon will be rendered by OpenGL but the order $\{v_0, v_1, v_2, v_3\}$ is different
- The first two describe *outwardly facing* polygons
- OpenGL can treat inward and outward facing polygons differently

- Use the *right-hand rule* =>



[Geometry vs Topology]

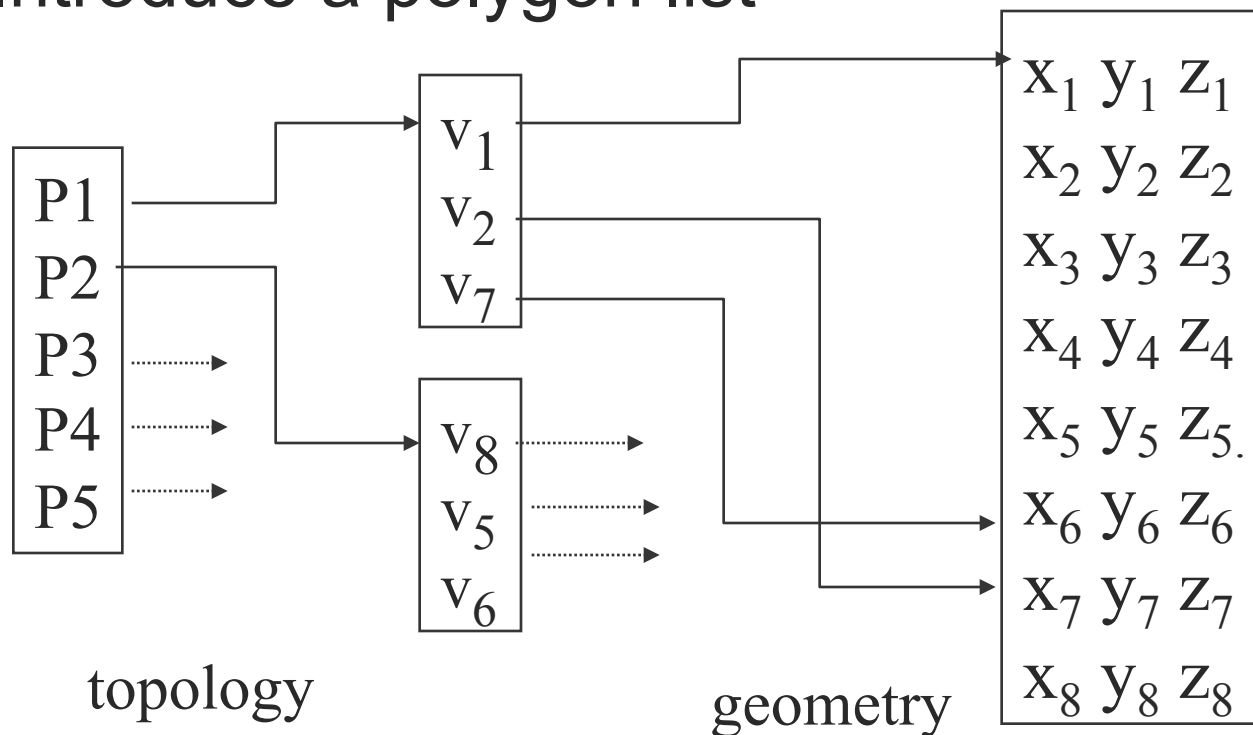
- Generally it is a good idea to look for data structures that separate the geometry from the topology
 - Geometry: locations of the vertices
 - Topology: organization of the vertices and edges
 - Topology holds even if geometry changes

[Geometry vs Topology]

- Example: a cube can be specified with `GL_QUADS` or `GL_POLYGON` 6 times
- Fails to capture the topology
 - A polyhedron with 6 faces.
 - Each face has 4 vertices
 - Each vertex share 3 faces

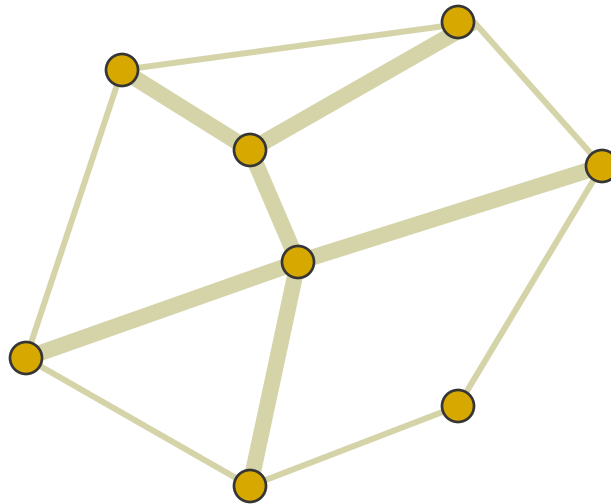
Vertex Lists

- Put the geometry in an array
- Use pointers from the vertices into this array
- Introduce a polygon list



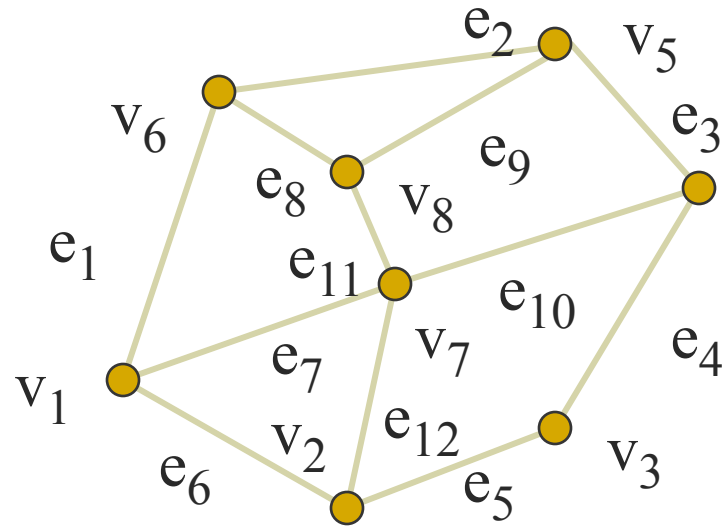
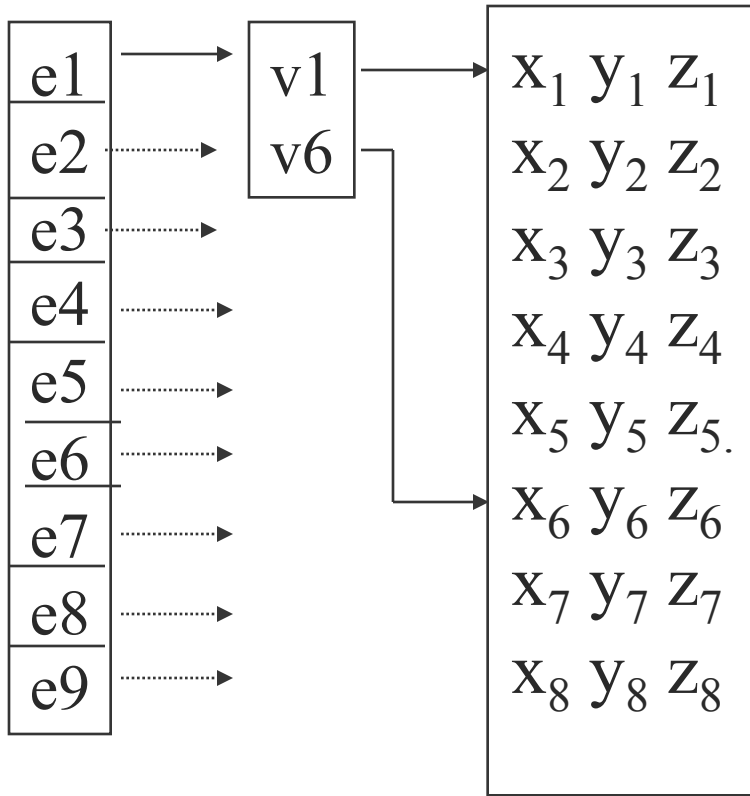
[Shared Edges]

- Vertex lists will draw filled polygons correctly but if we draw the polygon by its edges, shared edges are drawn twice



- Can store mesh by *edge list*

[Edge List]



Note polygons are not represented

[Modeling a Cube]

```
GLfloat vertices[][3] =  
{ {-1.0, -1.0, -1.0}, {1.0, -1.0, -1.0},  
  {1.0, 1.0, -1.0}, {-1.0, 1.0, -1.0}, {-1.0, -1.0, 1.0},  
  {1.0, -1.0, 1.0}, {1.0, 1.0, 1.0}, {-1.0, 1.0, 1.0}};
```

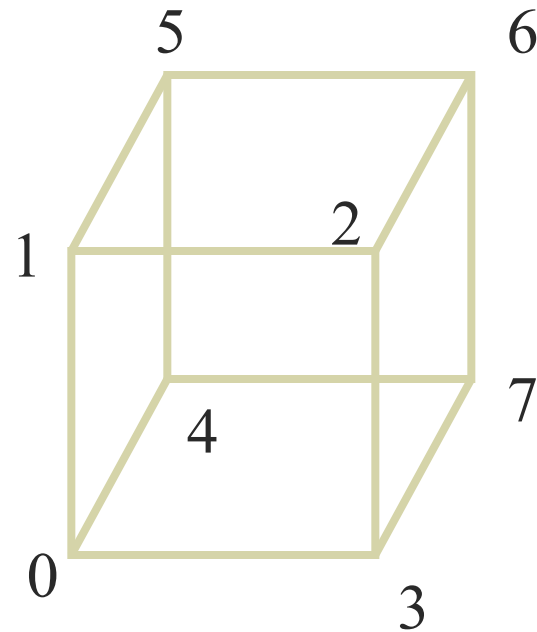
```
GLfloat colors[][3] =  
{ {0.0, 0.0, 0.0}, {1.0, 0.0, 0.0},  
  {1.0, 1.0, 0.0}, {0.0, 1.0, 0.0}, {0.0, 0.0, 1.0},  
  {1.0, 0.0, 1.0}, {1.0, 1.0, 1.0}, {0.0, 1.0, 1.0}};
```

Drawing a polygon from a list of indices

```
void polygon(int a, int b, int c , int d){
    glBegin(GL_POLYGON);
        glColor3fv(colors[a]);
        glVertex3fv(vertices[a]);
        glVertex3fv(vertices[b]);
        glVertex3fv(vertices[c]);
        glVertex3fv(vertices[d]);
    glEnd();
}
```

[Draw cube from faces]

```
void colorcube() {  
    polygon(0, 3, 2, 1);  
    polygon(2, 3, 7, 6);  
    polygon(0, 4, 7, 3);  
    polygon(1, 2, 6, 5);  
    polygon(4, 5, 6, 7);  
    polygon(0, 1, 5, 4);  
}
```



Note that vertices are ordered so that we obtain correct outward facing normals

[Efficiency]

- The weakness of our approach is that we are building the model in the application and must do many function calls to draw the cube
- Drawing a cube by its faces in the most straight forward way requires
 - 6 `glBegin`, 6 `glEnd`
 - 6 `glColor`
 - 24 `glVertex`
 - More if we use texture and lighting

[Vertex Arrays]

- OpenGL provides a facility called *vertex arrays* that allows us to store array data in the implementation
- Six types of arrays supported
 - Vertices
 - Colors
 - Color indices
 - Normals
 - Texture coordinates
 - Edge flags
- We will need only colors and vertices

Initialization

- Using the same color and vertex data, first we enable

```
glEnableClientState(GL_COLOR_ARRAY);  
glEnableClientState(GL_VERTEX_ARRAY);
```

- Identify location of arrays

```
glVertexPointer(3, GL_FLOAT, 0, vertices);
```

3d arrays

stored as floats

data contiguous

data array

```
glColorPointer(3, GL_FLOAT, 0, colors);
```

[Mapping indices to faces]

- Form an array of face indices

```
GLubyte cubeIndices[24] = {0, 3, 2, 1,  
                           2, 3, 7, 6,  
                           0, 4, 7, 3,  
                           1, 2, 6, 5,  
                           4, 5, 6, 7,  
                           0, 1, 5, 4};
```

- Draw through `glDrawElements` which replaces all `glVertex` and `glColor` calls in the display callback

[Drawing the cube]

- Method 1: what to draw number of indices

```
for(i=0; i<6; i++)  
    glDrawElements(GL_POLYGON, 4,  
                  GL_UNSIGNED_BYTE, &cubeIndices[4*i]);
```

format of index data

start of index data

- Method 2:

```
glDrawElements(GL_QUADS, 24,  
              GL_UNSIGNED_BYTE, cubeIndices);
```

Draws cube with 1 function call!!

[Idle Callback]

- Minimize the amount of computation done in an idle callback.
- If using idle for animation, stop rendering when nothing changed, or window not visible

```
glutVisibilityFunc(visible);  
void visible(int vis) {  
    if (vis == GLUT_VISIBLE)  
        glutIdleFunc(idle);  
    else  
        glutIdleFunc(NULL);  
}
```

[Back Face Culling]

- OpenGL can compute and remove those faces that are facing away from the viewer.
- `glEnable (GL_CULL) ;`

[Timer Callback]

- `void glutTimerFunc(unsigned int msec, void (*func)(int value), value);`
- Registers the timer callback `func` to be triggered in at least `msec` milliseconds.

```
#define FR 60
glutTimerFunc(100, myTimer, 0);
void myTimer(int v) {
    //update and advance states
    glutPostRedisplay();
    glutTimerFunc(1000/FR, myTimer, v);
}
```