

## CS206

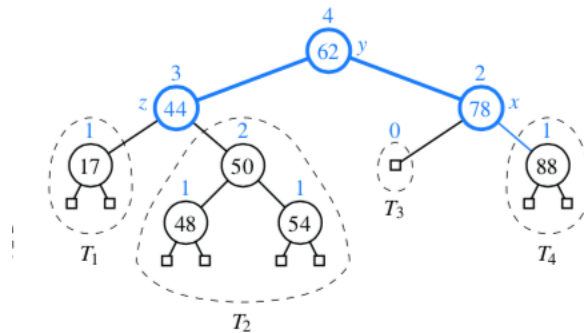
### Final set of review questions

#### Hashtables and Maps

- Which of the hash table collision-handling schemes could tolerate a load factor above 1 and which could not?
- Draw the 11-entry hash table that results from using the hash function,  $h(i) = (3i+5) \bmod 11$ , to hash the keys 12, 44, 13, 88, 23, 94, 11, 39, 20, 16, and 5, assuming collisions are handled by chaining.
- What is the result of the previous exercise, assuming collisions are handled by linear probing?
- Show the result of Q2 assuming collisions are handled by quadratic probing, up to the point where the method fails.
- What is the result of Exercise R-10.6 when collisions are handled by double hashing using the secondary hash function  $h'(k) = 7 - (k \bmod 7)$ ?
- What is the worst-case time for putting  $n$  entries in an initially empty hash table, with collisions resolved by chaining? What is the best case?
- Explain why a hash table is not suited to implement a sorted map.
- Describe how to perform a removal from a hash table that uses linear probing to resolve collisions where we do not use a special marker to represent deleted elements. That is, we must rearrange the contents so that it appears that the removed entry was never inserted in the first place.

## Binary Search Trees and AVL Trees

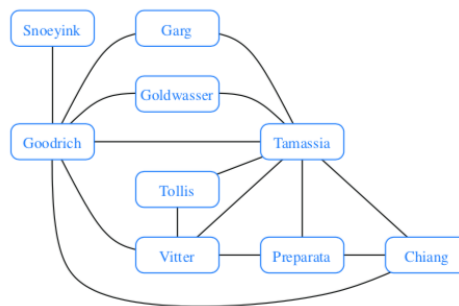
- If we insert the entries  $(1,A)$ ,  $(2,B)$ ,  $(3,C)$ ,  $(4,D)$ , and  $(5,E)$ , in this order, into an initially empty binary search tree, what will it look like?
- Insert, into an empty binary search tree, entries with keys 30, 40, 24, 58, 48, 26, 11, 13 (in this order). Draw the tree after each insertion.
- How many different binary search trees can store the keys  $\{1,2,3\}$ ?
- Dr. Amongus claims that the order in which a fixed set of entries is inserted into a binary search tree does not matter—the same tree results every time. Give a small example that proves he is wrong.
- Dr. Amongus claims that the order in which a fixed set of entries is inserted into an AVL tree does not matter—the same AVL tree results every time. Give a small example that proves he is wrong.



- Draw the AVL tree resulting from the insertion of an entry with key 52 into the AVL tree of the above figure.
- Draw the AVL tree resulting from the removal of the entry with key 62 from the AVL tree of Figure 11.13b.
- Explain why you would get the same output in an inorder listing of the entries in a binary search tree,  $T$ , independent of whether  $T$  is maintained to be an AVL tree, or not.
- Explain how to use an AVL tree or a to sort  $n$  comparable elements in  $O(n \log n)$  time in the worst case.

## Graphs

- Would you use the adjacency matrix structure or the adjacency list structure in each of the following cases? Justify your choice.
  - The graph has 10,000 vertices and 20,000 edges, and it is important to use as little space as possible.
  - The graph has 10,000 vertices and 20,000,000 edges, and it is important to use as little space as possible.
  - You need to answer the query  $\text{getEdge}(u, v)$  as fast as possible, no matter how much space you use.
- Explain why the DFS traversal runs in  $O(n^2)$  time on an  $n$ -vertex simple graph that is represented with the adjacency matrix structure.
- Computer networks should avoid single points of failure, that is, network vertices that can disconnect the network if they fail. We say an undirected, connected graph  $G$  is *biconnected* if it contains no vertex whose removal would divide  $G$  into two or more connected components. Give an algorithm for adding at most  $n$  edges to a connected graph  $G$ , with  $n \geq 3$  vertices and  $m \geq n-1$  edges, to guarantee that  $G$  is biconnected. Your algorithm should run in  $O(n + m)$  time.



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- Draw an adjacency matrix representation of the undirected graph shown above. You may add labels to links if you find it convenient
- Draw an adjacency list representation of the undirected graph shown above. You may add labels to links if you find it convenient
- Suppose we represent a graph  $G$  having  $n$  vertices and  $m$  edges with the edge list structure. Why, in this case, does the  $\text{insertVertex}$  method run in  $O(1)$  time while the  $\text{removeVertex}$  method runs in  $O(m)$  time
- Let  $G$  be an undirected graph with  $n$  vertices and  $m$  edges. Write a method traversing each edge of  $G$  exactly once in each direction. The method should run in  $O(m+n)$  time. You may use choose a graph representation. How would this algorithm be changed for a directed graph?

- Let  $G$  be an undirected graph whose vertices are the integers 1 through 8, and let the adjacent vertices of each vertex be given by the table below:

vertex

- 1 (2, 3, 4)
- 2 (1, 3, 4)
- 3 (1, 2, 4)
- 4 (1, 2, 3, 6)
- 5 (6, 7, 8)
- 6 (4, 5, 7)
- 7 (5, 6, 8)
- 8 (5, 7)

Assume that, in a traversal of  $G$ , the adjacent vertices of a given vertex are returned in the same order as they are listed in the table above.

- Draw  $G$ .
  - Give the sequence of vertices of  $G$  visited using a DFS traversal starting at vertex 1.
  - Give the sequence of vertices visited using a BFS traversal starting at vertex 1.
- The time delay of a long-distance call is determined by the number of communication links on the telephone network between the caller and callee. The engineers of RT&T want to compute the maximum possible time delay that may be experienced in a long-distance call. Write method that computes the **maximum** number of links (when cycles are disallowed, between some caller A and every other caller).
  - For the implementation of Graph, Link and Node add a method
 

```
public void removeLink(Link<E> link)
```

 in an appropriate place. Where is that “appropriate” place?
  - Reimplement Dijkstra’s shortest path method (in the Graph class on the class website) using a Stack rather than a Priority Queue. Doing so saves some time in that stacks have  $O(1)$  time for push and pop whereas PriorityQueues have  $O(\lg n)$  time for the equivalent operations. How do the other adjustments you needed to make to the function to ensure that you got the shortest path affect its runtime?
  - Write a method to do a breadth first traversal for a graph (starting at a node). Why might a breadth first traversal be preferred to a depth first traversal?