

CMSC 110 Introduction to Computing Section 01

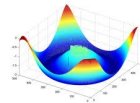
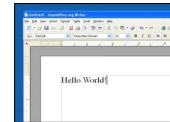
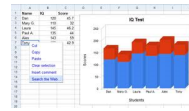
Dianna Xu

What is Computing?

Computing: Web, e-mail, social...



Computing: Productivity...

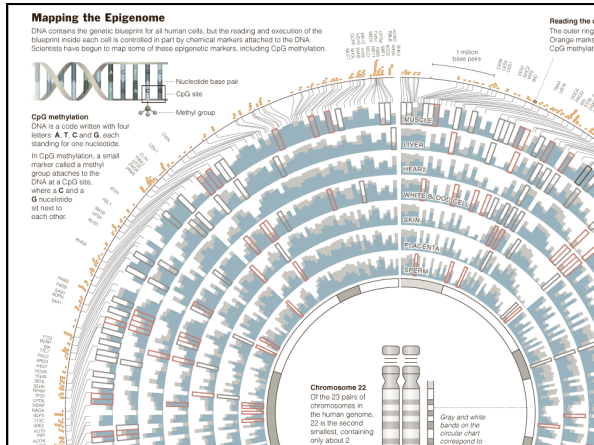
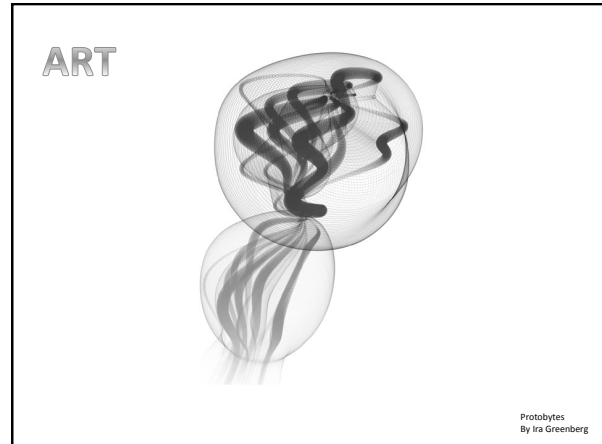
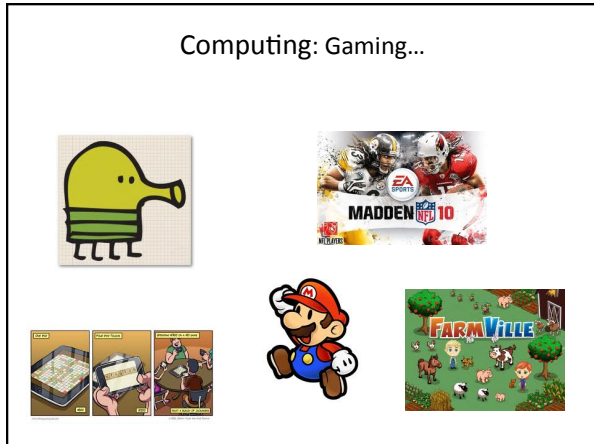


Computing: Digital Photography



Computing: Entertainment...





Computing is important.

Fastest Growing Occupations

Table 1.3 Fastest growing occupations, 2008 and projected 2018
(Numbers in thousands)

2008 National Employment Matrix title and code	Employment		Change, 2008-18		Median Annual wage quartile, 2008
	2008	2018	Number	Percent	
Network systems and data communications analysts	292.0	447.8	155.8	53.36	VH
Computer software engineers, applications	514.8	689.9	175.1	34.01	VH
Computer software engineers, systems software	394.8	515.0	120.2	30.44	VH

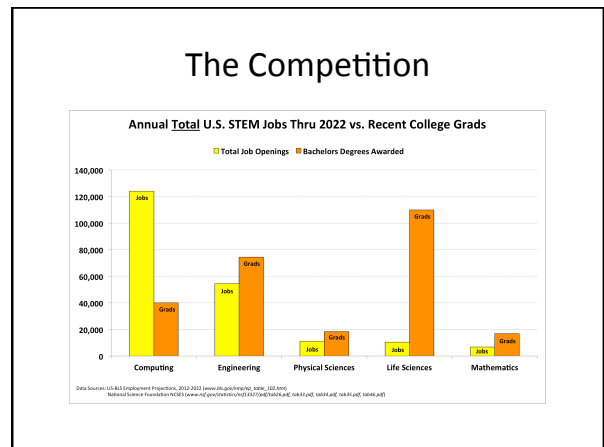
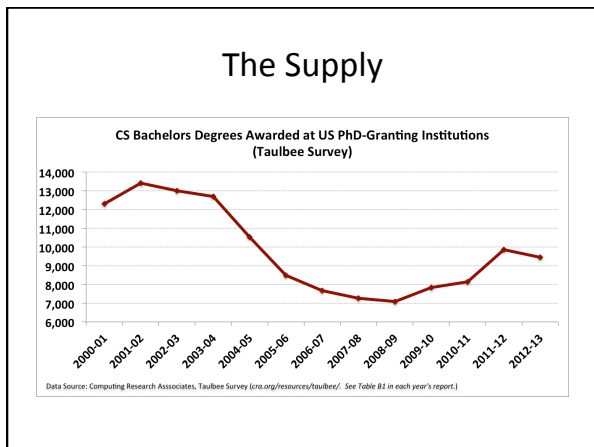
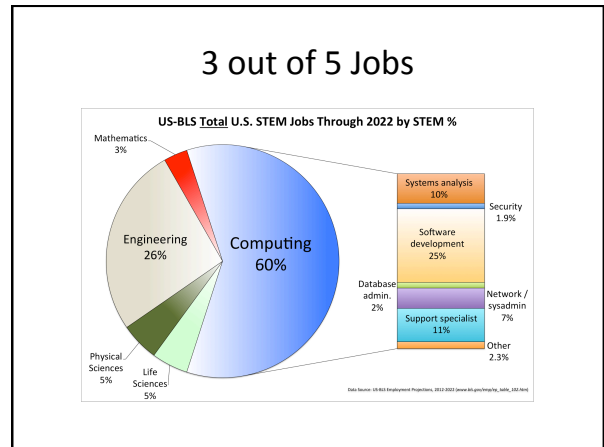
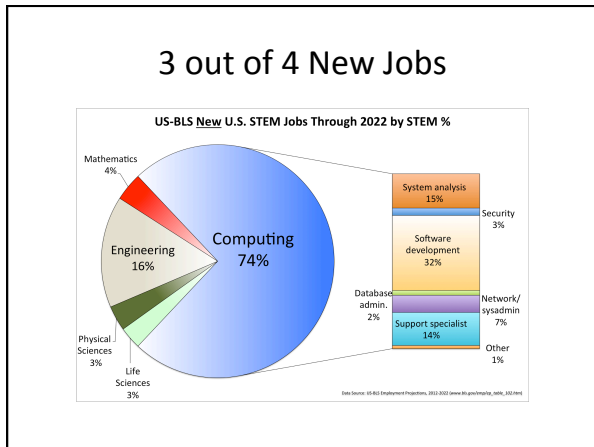
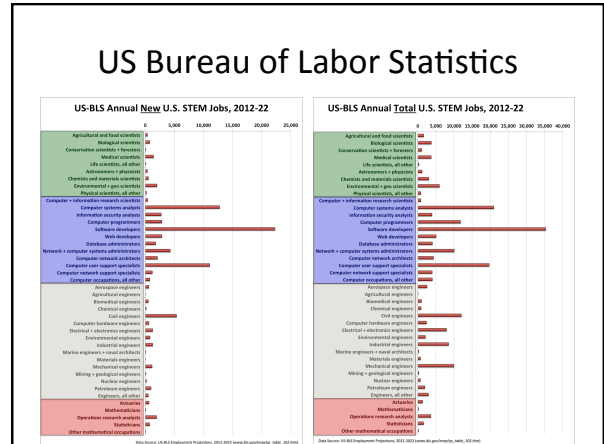
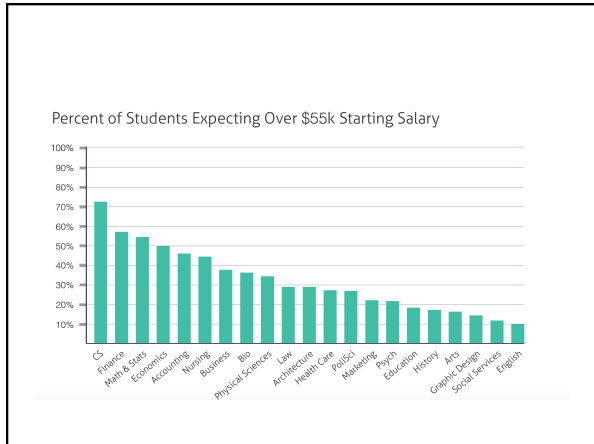
Source: Employment Projections Program, U.S. Department of Labor, U.S. Bureau of Labor Statistics

Occupational Outlook Handbook, 2010-11 Edition, http://www.bls.gov/emp/ep_table_103.htm

2015 Survey of 50,000 College Grads

- 54.6% of the class of 2014 are unemployed
- Of those that do have jobs...

<https://www.looksharp.com/blog/what-50000-students-have-to-say-about-college-recruiting>



What can be programmed?



Autonomous Driving

Google's modified Toyota Prius uses an array of sensors to navigate public roads without a human driver. Other components, not shown, include a GPS receiver and an inertial motion sensor.

LiDAR
A rotating sensor on the roof scans more than 200 feet in all directions to generate a precise three-dimensional map of the car's surroundings.

POSITION ESTIMATOR
A sensor mounted on the left rear wheel measures small movements made by the car and helps to accurately locate its position on the map.

VIDEO CAMERA
A camera mounted near the rear-view mirror detects traffic lights and helps the car's onboard computers recognize moving obstacles like pedestrians and bicyclists.

RADAR
Four standard automotive radar sensors, three in front and one in the rear, help determine the positions of distant objects.

Source: Google

Photovoltaic generation, Rooftop planting, Improving insulation, Automated ventilation control, Lighting control using natural light, High-efficiency light fixtures, Restriction of sunlight, Rainwater utilization systems, High-efficiency heating equipment.

Conceptual Drawing of Green Building

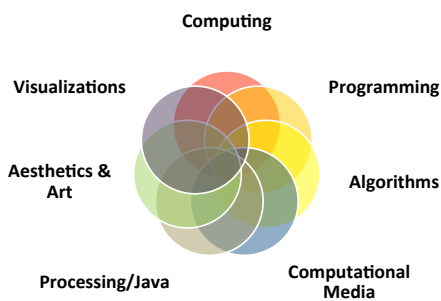
How do you program?



What is a Computer Program?

A collection of human readable statements that can be translated to machine instructions and executed by a computing device.

Introduction to ^{Creative} Computing

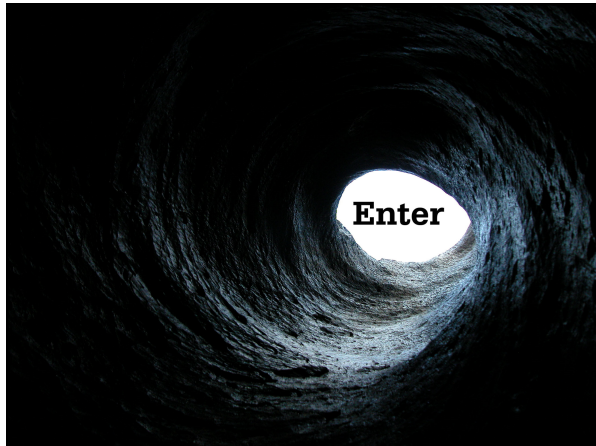


Our Goal

- Use computing to realize works of art
- Explore new metaphors from computing: images, animation, interactivity, visualizations
- Learn the basics of computing
- Have fun doing all of the above!

Why?

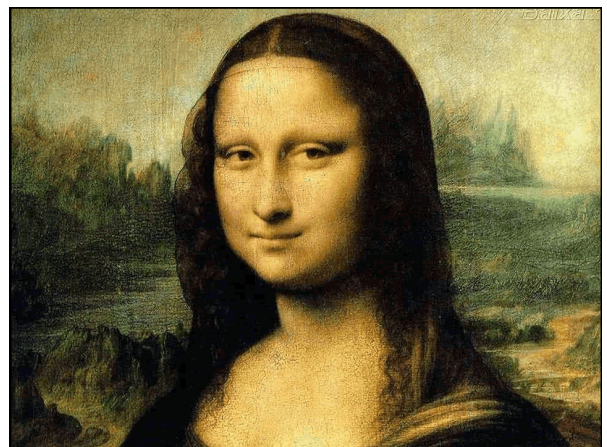




Examples



Obamicons





Summertime

Summertime,
 And the livin' is easy
 Fish are jumpin'
 And the cotton is high

Your daddy's rich
 And your mamma's good lookin'
 So hush little baby
 Don't you cry

One of these mornings
 You're going to rise up singing
 Then you'll spread your wings
 And you'll take to the sky

But till that morning
 There's a'nothin' can harm you
 With daddy and mamma standing by

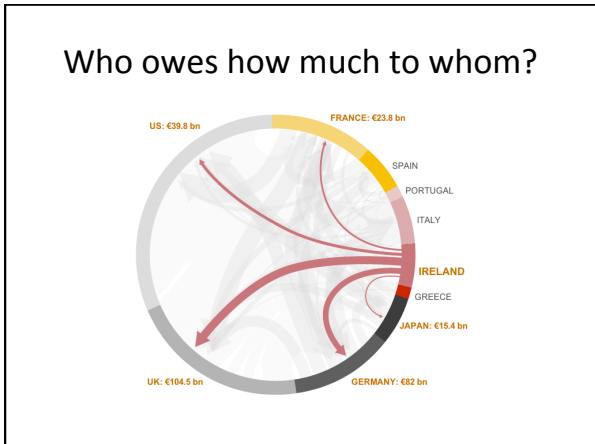
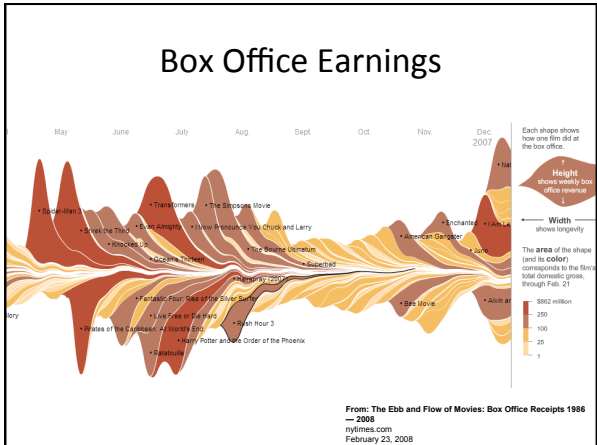
Summertime,
 And the livin' is easy
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 Don't you cry

Lyrics by George Gershwin

Word Cloud

Created using: wordle.net



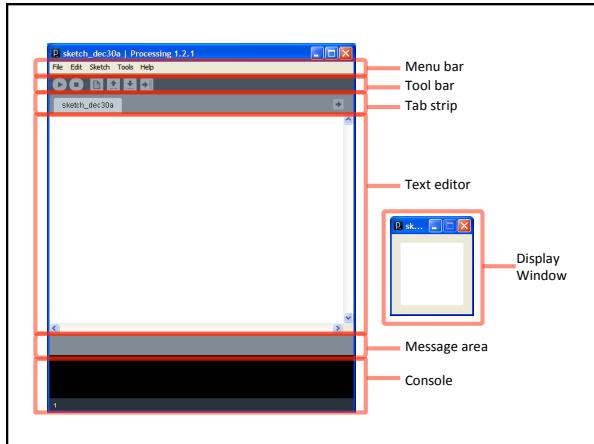
Software

Processing

- Already installed in the CS Lab
- Also available for your own computer @ www.processing.org
- Processing == Java

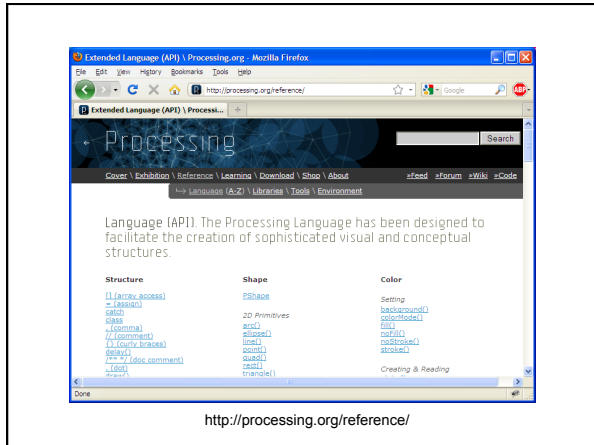
Book

Processing: Creative Coding & Generative Art in Processing 2
 Friends of ed, 2013.



Primitive 2D Shapes

- point
- line
- triangle
- rect (rectangle)
- quad (quadrilateral, four-sided polygon)
- ellipse
- arc (section of an ellipse)
- curve (Catmull-Rom spline)
- bezier (Bezier curve)



Anatomy of a Function Call

Function name Parentheses

line (10, 10, 50, 80);

Arguments Statement terminator

A diagram illustrating the components of a function call. Red arrows point from labels to parts of the code: "Function name" points to "line", "Parentheses" points to the opening and closing parentheses, "Arguments" points to the values "10, 10, 50, 80", and "Statement terminator" points to the semicolon.

Coordinate System

(0, 0)

+x

+y

A diagram of a 2D Cartesian coordinate system. The origin is labeled "(0, 0)". The horizontal axis is labeled "+x" and the vertical axis is labeled "+y".

Pixels

A screenshot of a photo of a large green tree in a field. A circular area of the tree's foliage is magnified, showing a grid of individual pixels, illustrating how a continuous image is composed of discrete points.

Processing Canvas

```
size( width, height );
```

Set the size of the canvas.

```
background( [0..255] );
```

Set the background grayscale color.

Drawing Primitives

```
point( x, y );
```

```
line( x1, y1, x2, y2 );
```

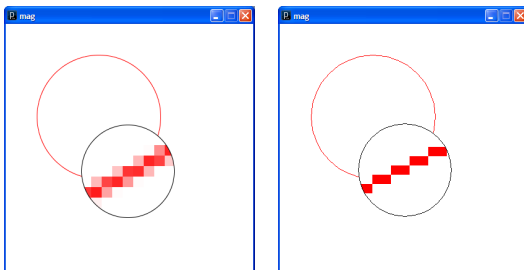
```
triangle( x1, y1, x2, y2, x3, y3 );
```

```
quad( x1, y1, x2, y2, x3, y3, x4, y4 );
```

```
rect( x, y, width, height );
```

```
ellipse( x, y, width, height );
```

smooth() vs. noSmooth()



Colors

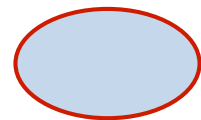
Composed of four elements:

1. Red
2. Green
3. Blue
4. Alpha (Transparency)

Why 0 .. 255?

Shape Formatting

1. Fill color
2. Line thickness
3. Line color



*These are properties of your paintbrush,
not of the object you are painting.*



Fill Color

```
fill(gray);
fill(gray, alpha);
fill(red, green, blue);
fill(red, green, blue, alpha);

noFill();
```



Stroke (Line) Color

```
stroke(gray);
stroke(gray, alpha);
stroke(red, green, blue);
stroke(red, green, blue, alpha);

noStroke();
```



strokeCap()



```
smooth();
strokeWeight(12.0);
strokeCap(ROUND);
line(20, 30, 80, 30);
strokeCap(SQUARE);
line(20, 50, 80, 50);
strokeCap(PROJECT);
line(20, 70, 80, 70);
```

strokeWeight()



```
smooth();
strokeWeight(1); // Default
line(20, 20, 80, 20);
strokeWeight(4); // Thicker
line(20, 40, 80, 40);
strokeWeight(10); // Beastly
line(20, 70, 80, 70);
```

http://processing.org/reference/strokeCap_.html
http://processing.org/reference/strokeWeight_.html

ellipseMode



```
ellipseMode(CENTER);
ellipse(35, 35, 50, 50);
ellipseMode(CORNER);
fill(102);
ellipse(35, 35, 50, 50);
```

rectMode



```
rectMode(CENTER);
rect(35, 35, 50, 50);
rectMode(CORNER);
fill(102);
rect(35, 35, 50, 50);
```

http://processing.org/reference/ellipseMode_.html
http://processing.org/reference/rectMode_.html

Dropbox

- <https://www.dropbox.com/>